



HIERARCHICAL SYSTEM MODELING

Lecture 2.1

Modelon

OVERVIEW

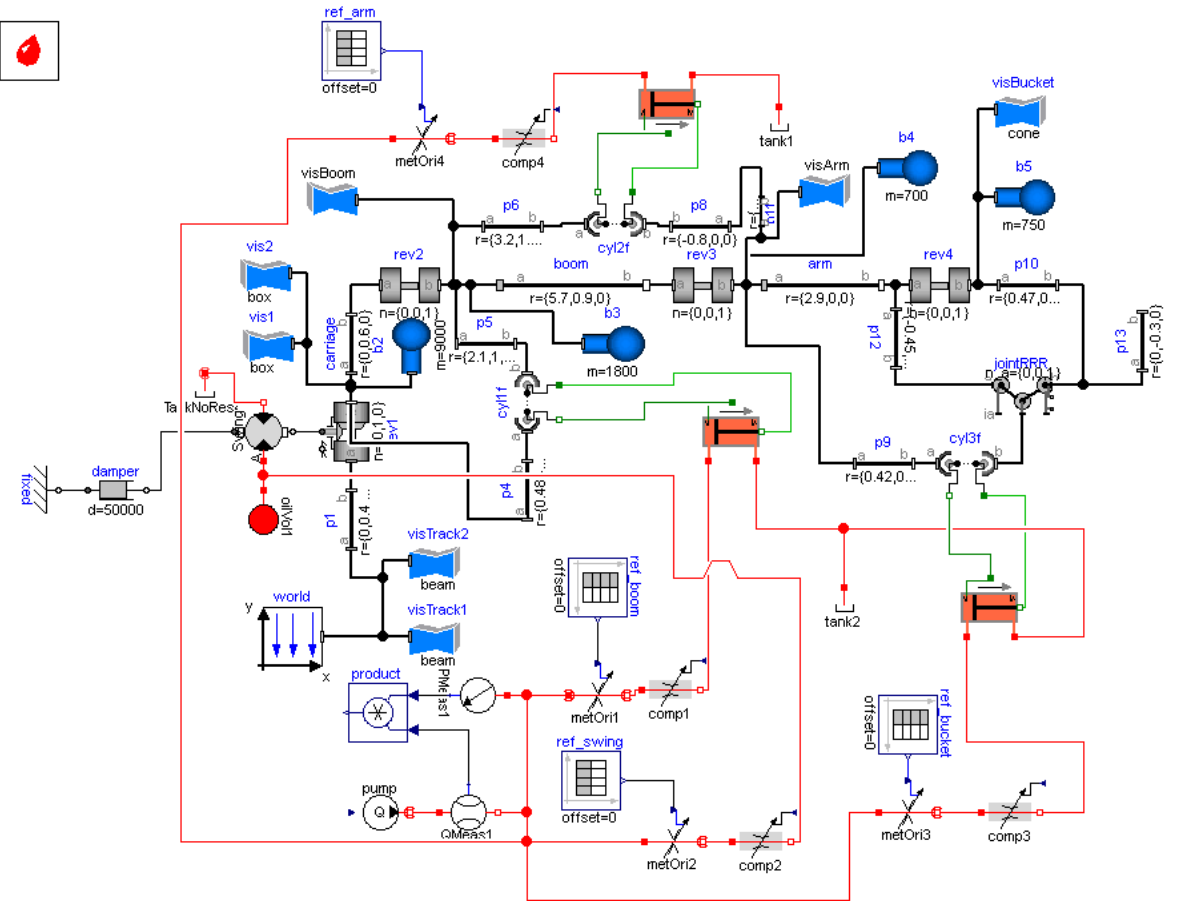
- ✓ Benefits with hierarchical models
- ✓ Library Architecture and Model Structure
- ✓ Browse model hierarchy
- ✓ Parameter propagation and modifiers
- ✓ Reconfigurable models
- ✓ System stickies and views



BENEFITS WITH HIERARCHICAL MODELS

FLAT VS. STRUCTURED MODEL

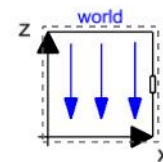
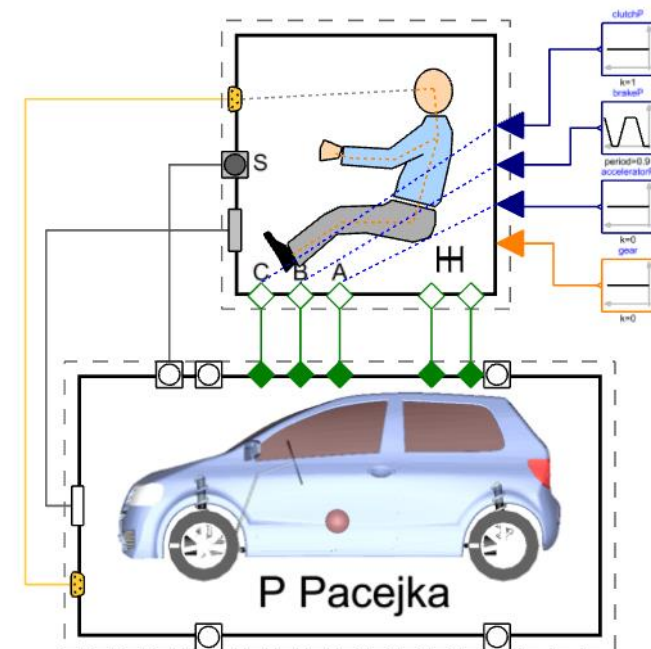
- Example of a hydraulic excavator
 - flat structure
 - one level for all components
 - no structural distinction between different domains as well as experiment boundary conditions
 - difficult to quickly understand the basic idea of the model for someone who has not created it



FLAT VS. STRUCTURED MODEL

Example of a driver - passenger car experiment

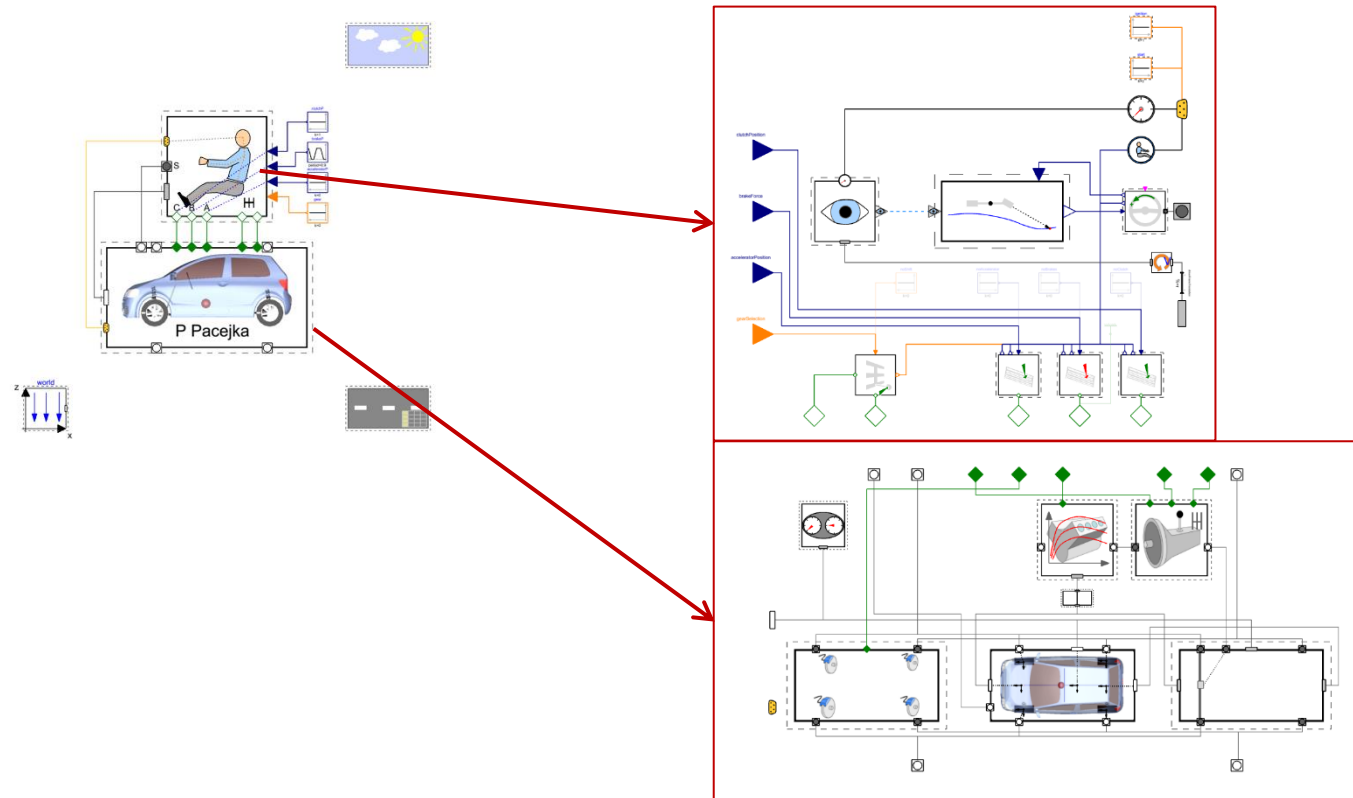
- Modular system decomposition makes reuse and exchange of system parts easier.



FLAT VS. STRUCTURED MODEL

Example of a driver - passenger car experiment

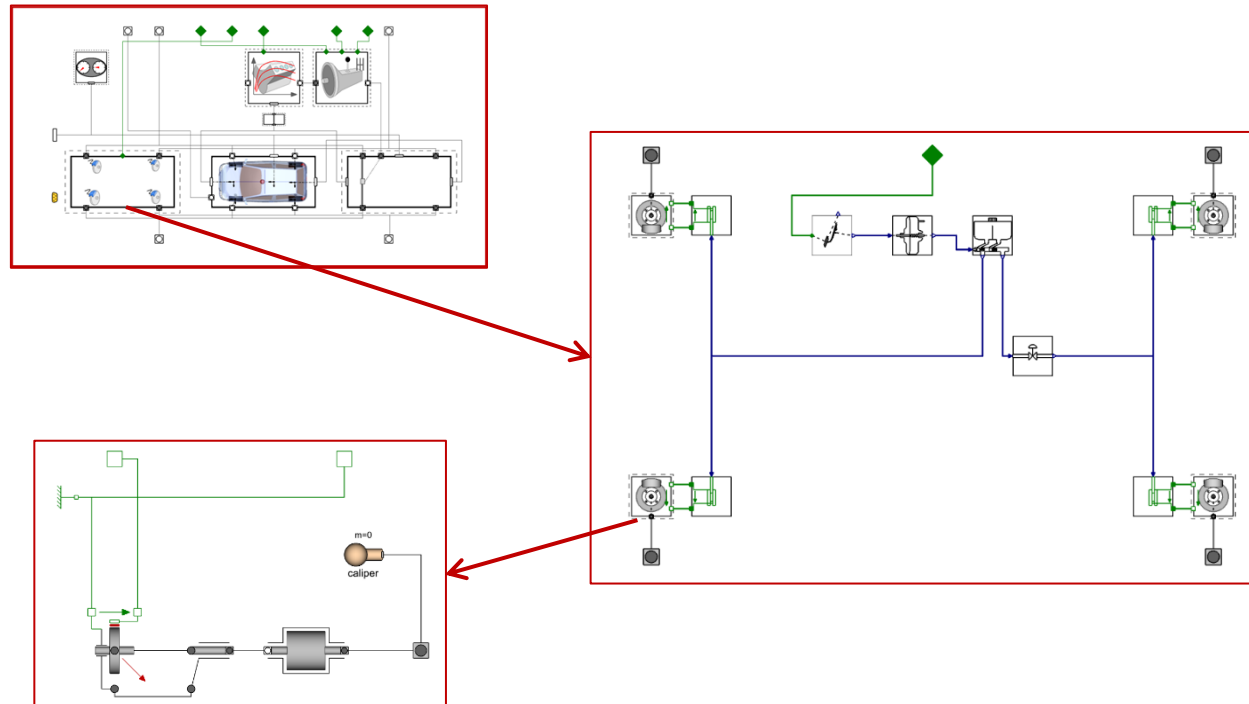
- Modular system decomposition makes reuse and exchange of system parts easier.
- Individual components are grouped into subsystems.



FLAT VS. STRUCTURED MODEL

Example of a driver - passenger car experiment

- Modular system decomposition makes reuse and exchange of system parts easier.
- Individual components are grouped into subsystems.
- Physical interaction comprehensible from the graphical view.



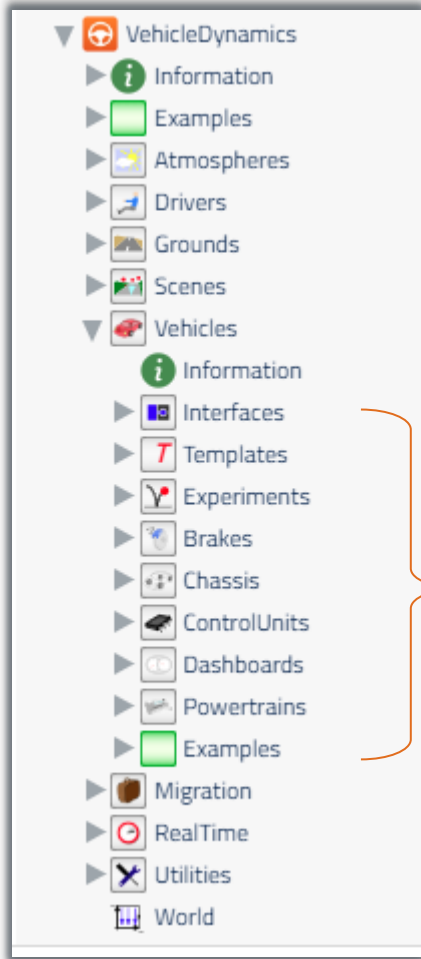


LIBRARY ARCHITECTURE AND MODEL STRUCTURE

FEATURES OF A GOOD MODEL LIBRARY

- If a large complex system model can be used and understood by someone other than the person who modeled it
 - The structure of the real-world system is reflected
 - Physical component interactions can be recognized easily in the graphical view
 - The system model can be graphically reconfigured and adapted to different boundary conditions
- Model classes are easy to find
 - Well organized package structure with descriptive names

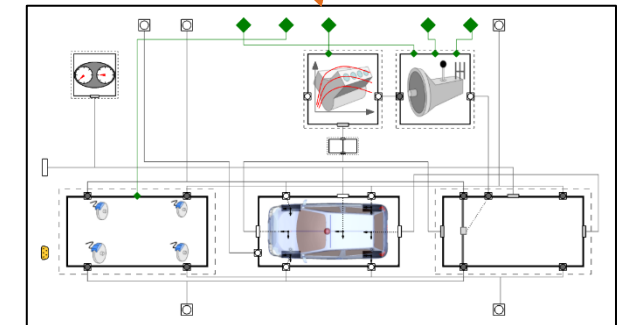
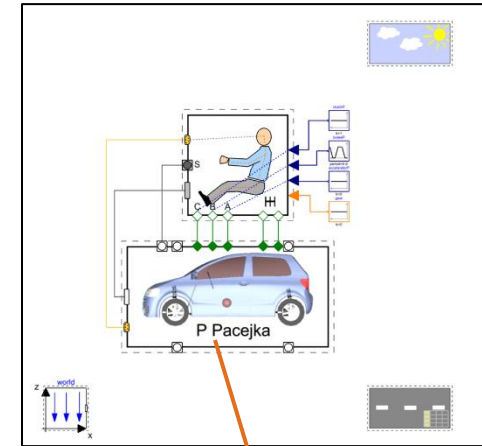
PACKAGE STRUCTURE



Good modeling practice:

- Package structure resembles system structure to a certain extent
- Within reasonable depths, i.e., only upper levels

Example: Sub-systems within *Vehicle* package correspond to components in diagram view of a vehicle





BROWSE MODEL HIERARCHY

CLASS VS. COMPONENT

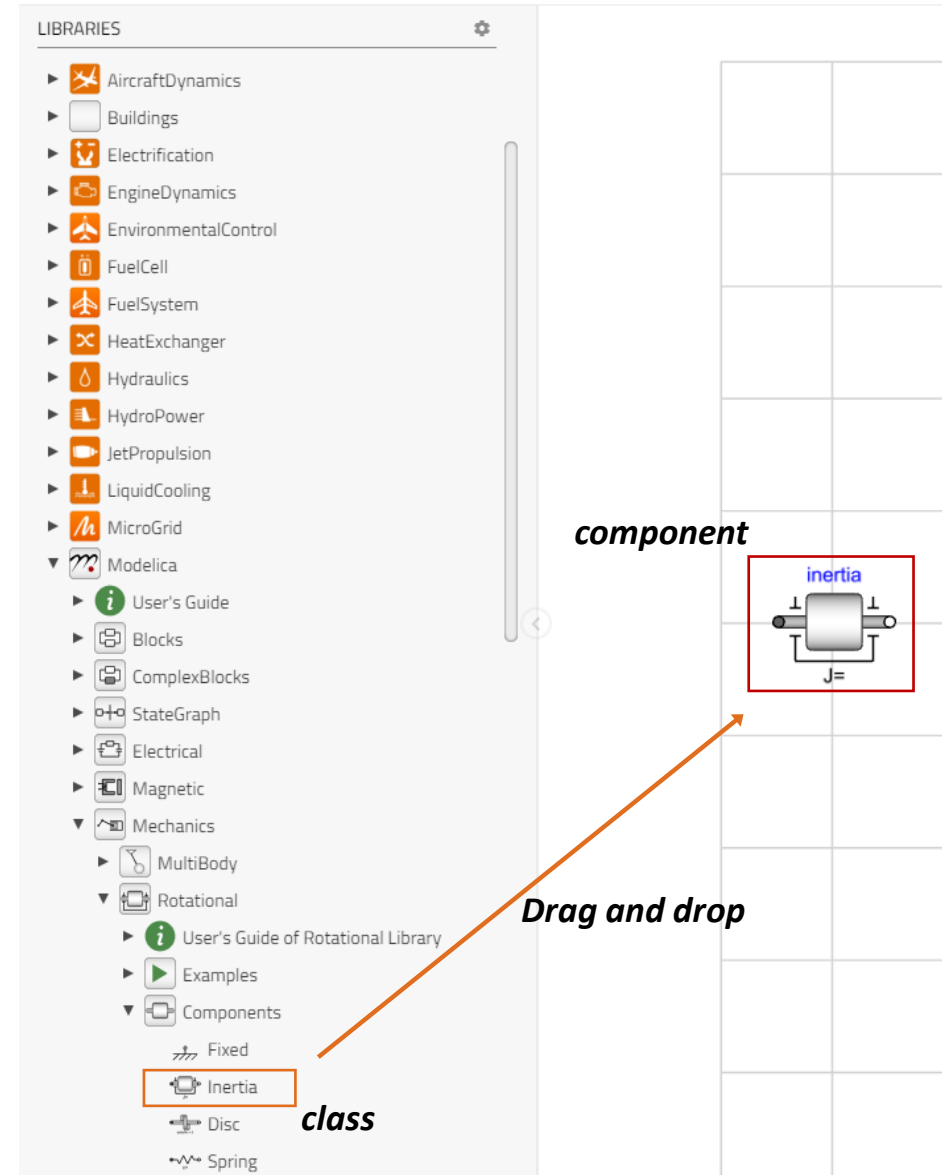
- Class
 - *Modelica* keyword
 - model, connector, package, type...
 - defines behavior
 - convention: name starts with upper case
- Component
 - not a Modelica word
 - instance of a class
 - convention: name starts with lower case

Modelica text view:

```
model Unnamed
  .Modelica.Mechanics.Rotational.Components.Inertia inertia;
end Unnamed;
```

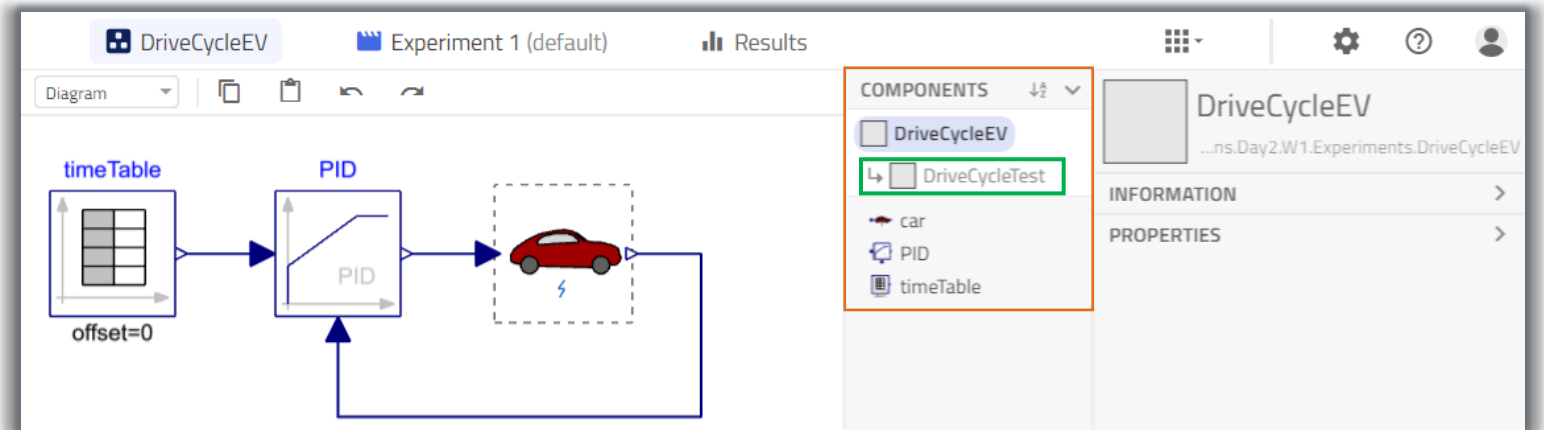
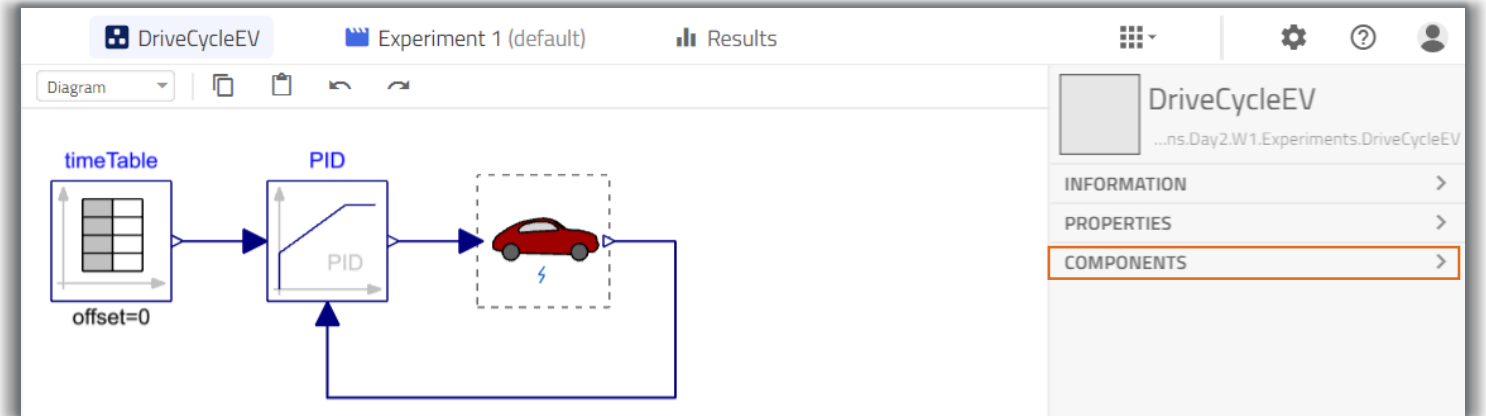
component
instance name

class
name



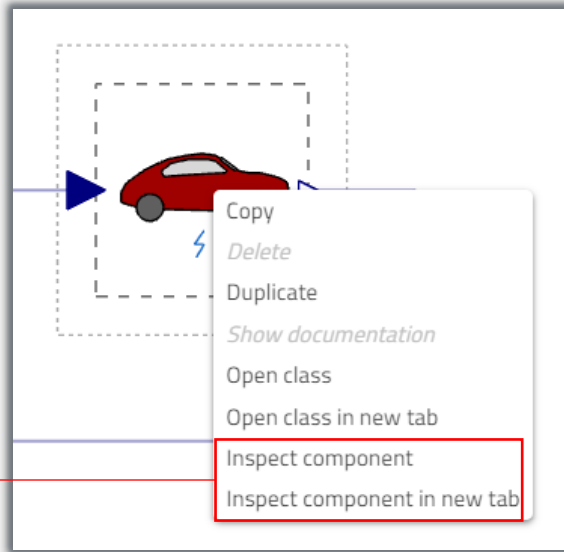
COMPONENT BROWSER

- We saw that Modelica enables hierarchical modeling – you can inspect the contents/hierarchy of a model using the *Components Browser*
- It is available for all three modes
- Useful to get an overall idea of the components present in the model
- It also shows any classes the current model extends

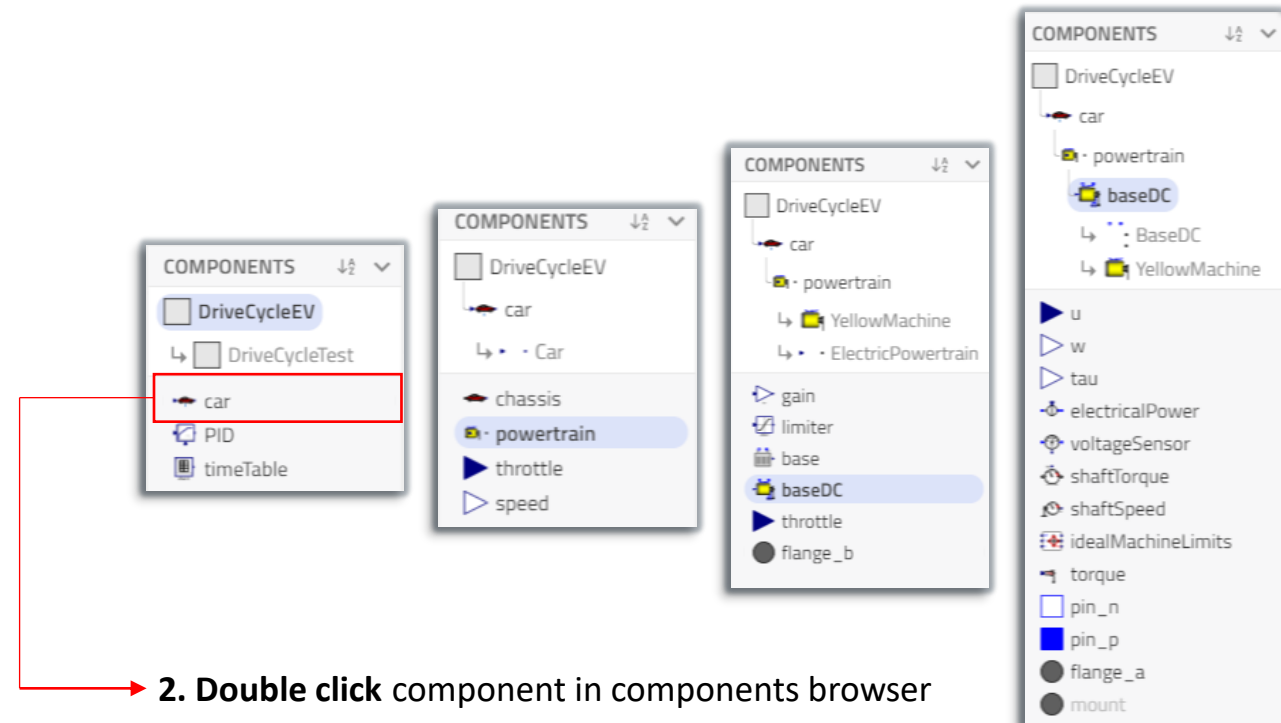


INSPECT COMPONENT

- Inspecting a component helps understand what components are present inside it
- Modelon Impact allows you to go down in the hierarchy in two ways:



1. Right-click the component on canvas then **Inspect component** or **Inspect component in new tab**



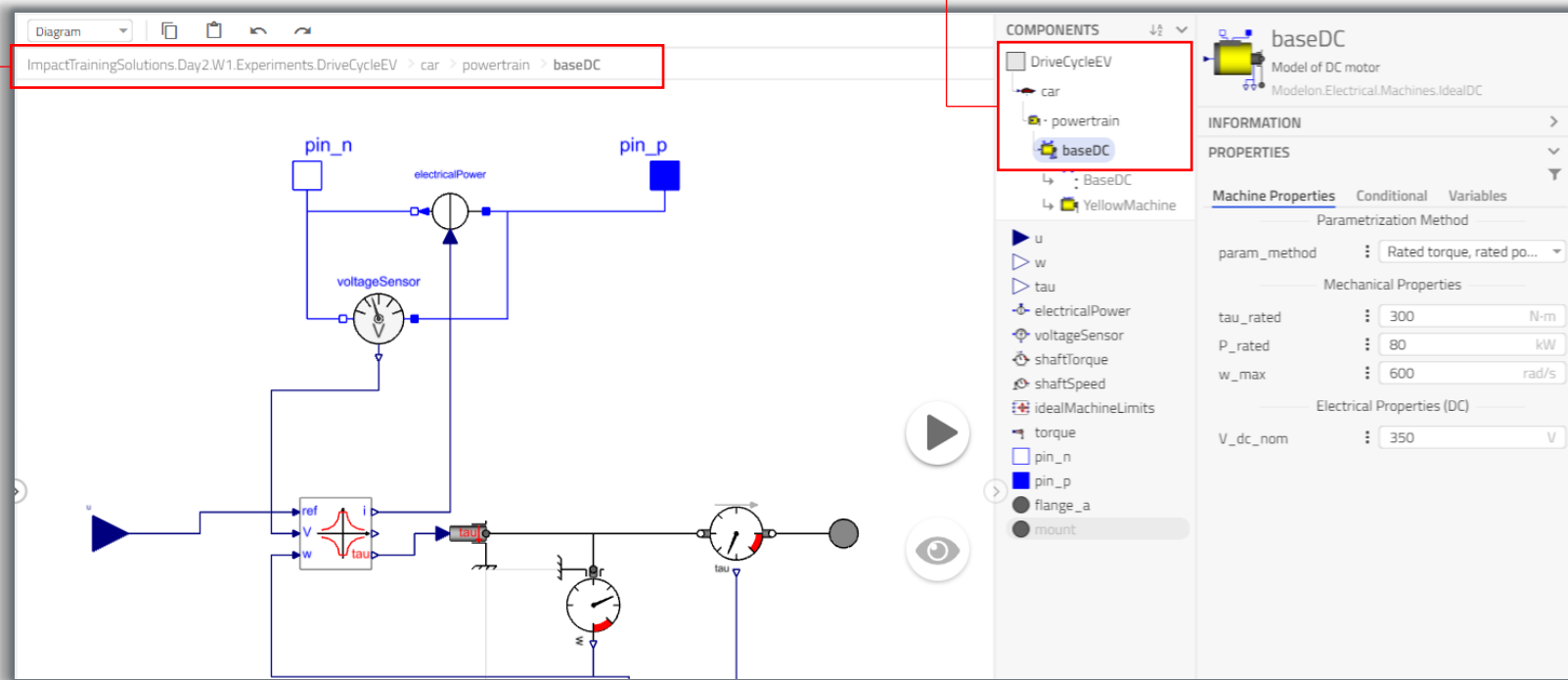
2. Double click component in components browser

BROWSE INSTANCE TREE

- To go back up, click on any of the **Bread-crumbs**

Bread-crumbs

Hierarchy





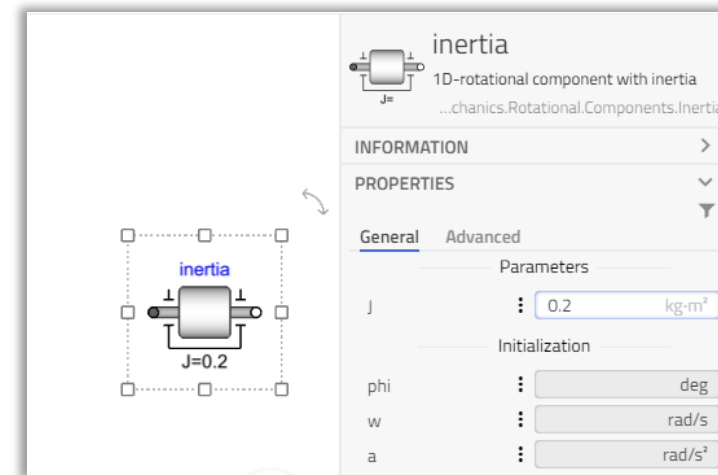
PARAMETER PROPAGATION AND MODIFIERS

WHAT ARE MODIFIERS?

- "A modifier is a Modelica language construct that allows to modify an existing class by setting a variable, parameter or attribute value, by binding a parameter or variable to an expression containing other parameters or to change a class reference to another class."

- Examples:

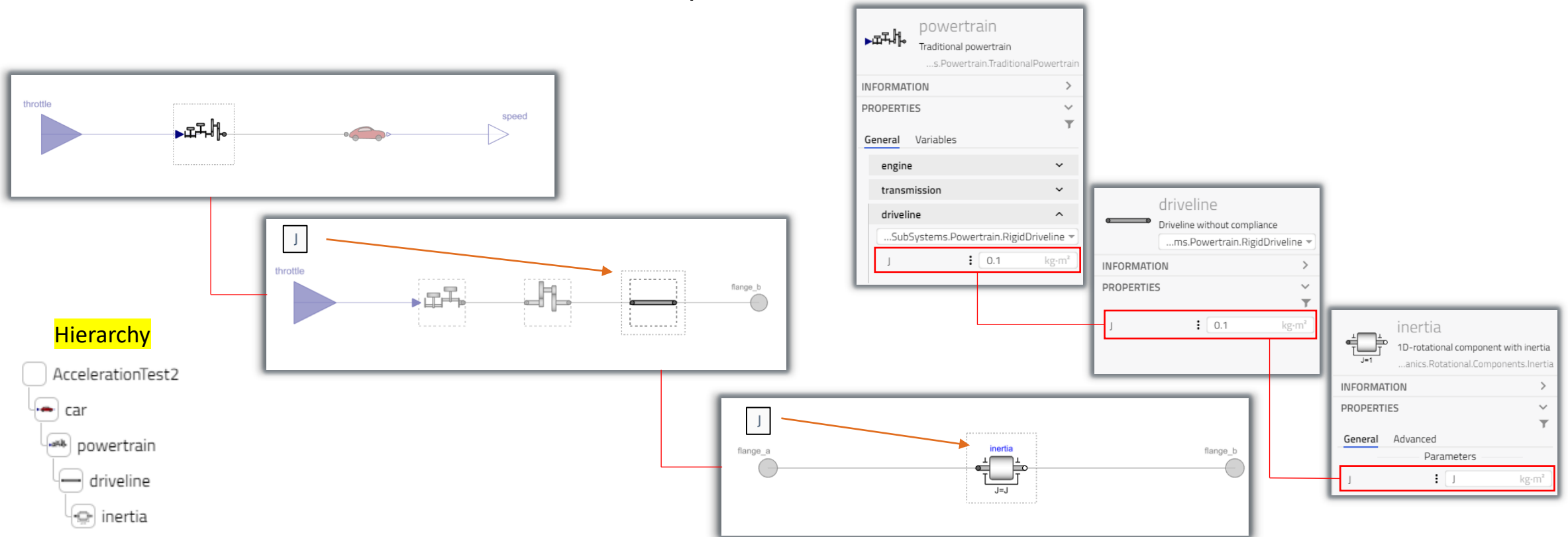
- Simple parameter modifier: *inertia(J = 0.2)*



- Class modifier: *extends Template.FullCarAccelerationTest(redeclare Systems.OriginalCarConfig car, throttle(k=1))*
- Binding equation: *volume(v = tank.level*tank.crossArea)*

MODIFIERS

- The preferred workflow to create a proper data flow through the model tree is parameter propagation
- This was introduced in lecture Reusable Components



HIERACHICAL MODIFIERS IN SYSTEM MODELS

- A "system model" here is a fully-paramatrized model ready to be simulated
- You can modify any part of the final model
 - Modifier only resides within the experiment container
 - In the example, the modified value of **350** for the parameter **tau_max** is only applicable to the particular experiment – **DriveCycleTest**


The screenshot shows a software interface for a system model. On the left, a 'COMPONENTS' tree displays a hierarchy: DriveCycleTest (containing car, powertrain, baseDC, BaseDC, and YellowMachine), electricalPower, u, voltageSensor, shaftTorque, tau, w, shaftSpeed, and idealMachineLimits. The 'idealMachineLimits' component is selected, and its properties are shown on the right. The 'LIMITS' section includes: enable_tau_max (checked), enable_P_max (unchecked), tau_max (350 N·m), I_dc_max (if param_method == 1 the A), P_max (P_rated W), V_dc_min (1 V), and enable_events (unchecked).

```
TrainingPack.W3.Experiments.DriveCycleTest
(read-only)

1      model DriveCycleTest
2      extends .TrainingPack.W3.Experiments.Template.DriveCycleTest(redeclare replaceable
3      .TrainingPack.W3.Systems.ElectricCar car(powertrain(baseDC(idealMachineLimits(tau_max=350))));
4      end DriveCycleTest;
```

HIERARCHICAL MODIFIERS IN SYSTEM MODELS

- If modifiers are applied in the modeling mode, its stored in the modelica code



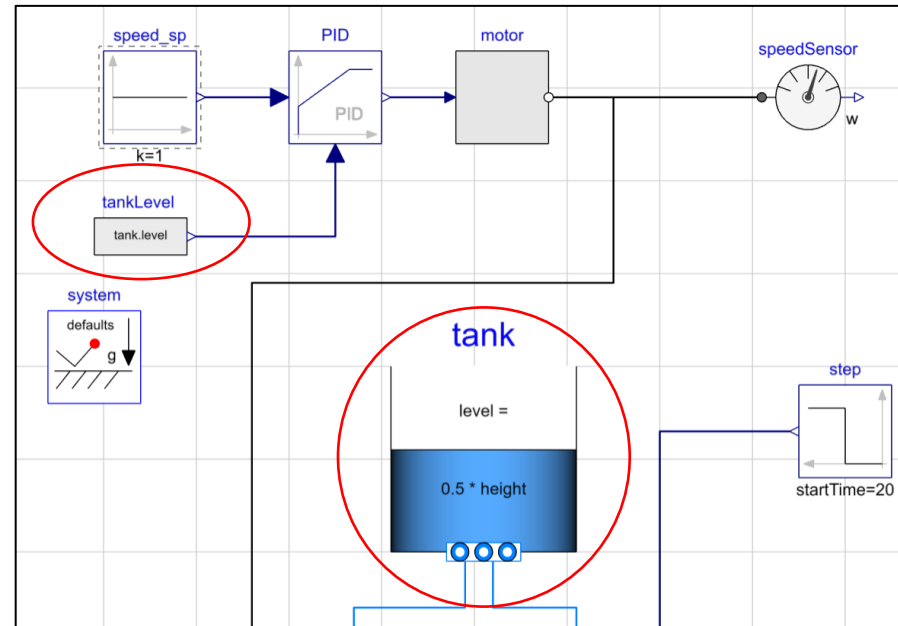
The screenshot shows the Modelon software interface. At the top, there are three tabs: 'DriveCycleTest' (selected), 'Experimentation', and 'Results'. Below the tabs, a code editor displays the following Modelica code for 'TrainingPack.W3.Experiments.DriveCycleTest (read-only)':

```
1      model DriveCycleTest
2          extends .TrainingPack.W3.Experiments.Template.DriveCycleTest(redeclare replaceable
3              .TrainingPack.W3.Systems.ElectricCar car(powertrain(baseDC(idealMachineLimits(tau_max=350)))));
4      end DriveCycleTest;
```

- If modification is done in Experimentation mode, it will be stored in that specific Experiment definition.

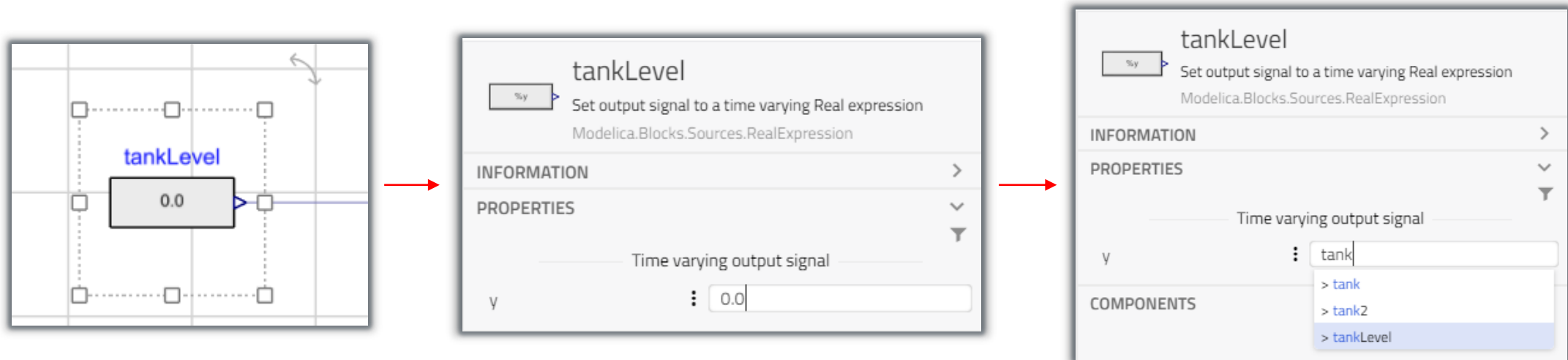
MODIFIERS BY COMPONENT REFERENCE

- Component reference is an option when you want to define variables by referencing variables or parameters from other components
- Data for the referenced variable is automatically retrieved (from the model instance tree)
 - In the example, value of ***tank.level*** (level of fluid in the tank) has been used in a **realExpression** block



MODIFIERS BY COMPONENT REFERENCE

- Modification by component reference can be done by browsing or autocompletion
 1. Select the component where a parameter needs to be modified
 2. Go to **Details Panel-> Properties**
 3. Start typing the parameter by dot notation
 - Start typing to enable instance browser
 - Use arrow keys + (enter or tab)

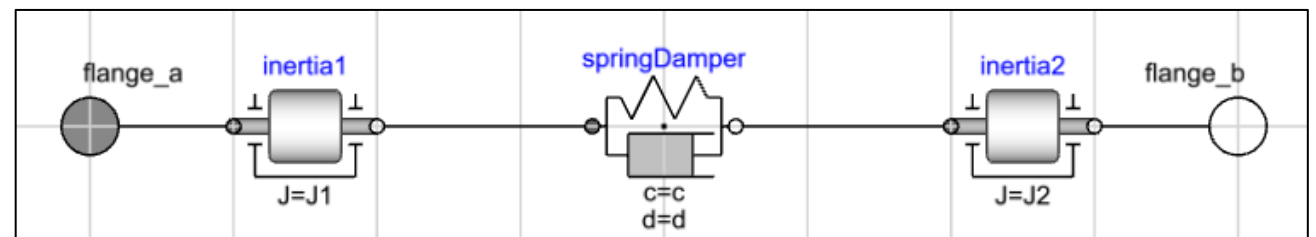
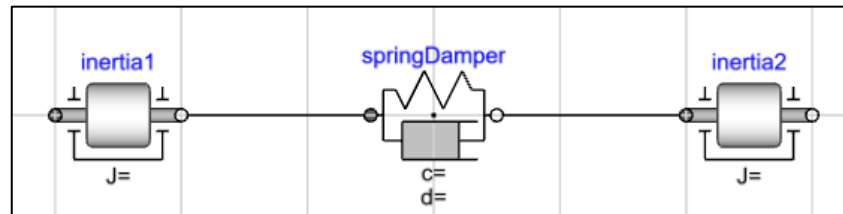




RECONFIGURABLE MODELS

INTERFACING A COMPONENT

- When creating a new component or subsystem you need to design its interface
 - Connector interface (how it interacts physically)
 - Parameter interface (what data is needed)

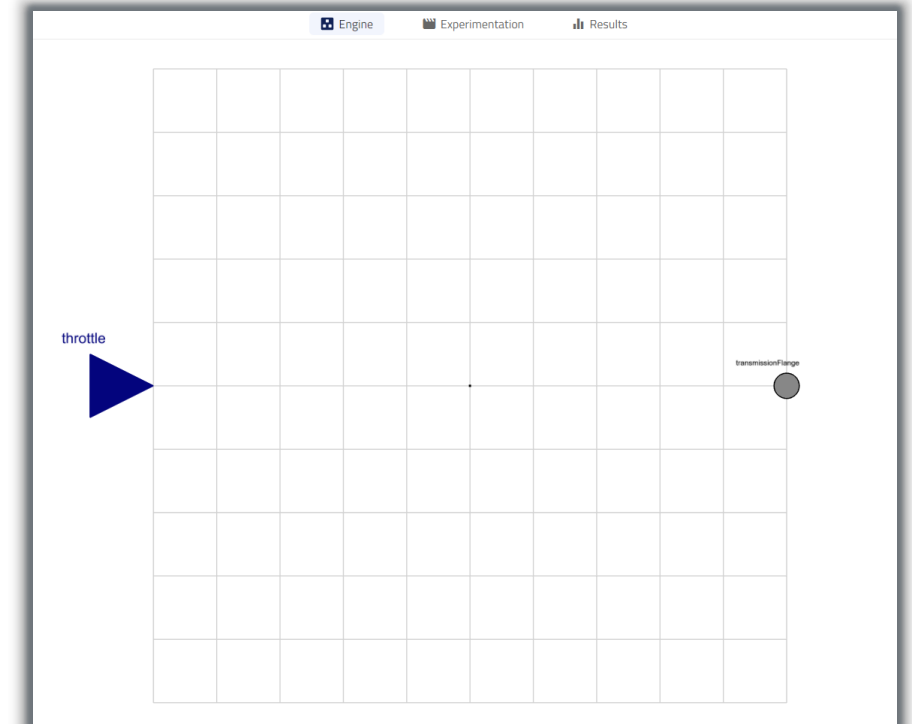


INTERFACE CLASSES

- An interface contains
 - Connectors
 - Common parameters
- Well-defined interfaces ensure plug-compatibility: all models that share an interface will also fit in the template
- Interfaces are used with inheritance, in Modelica the keyword is 'extends'

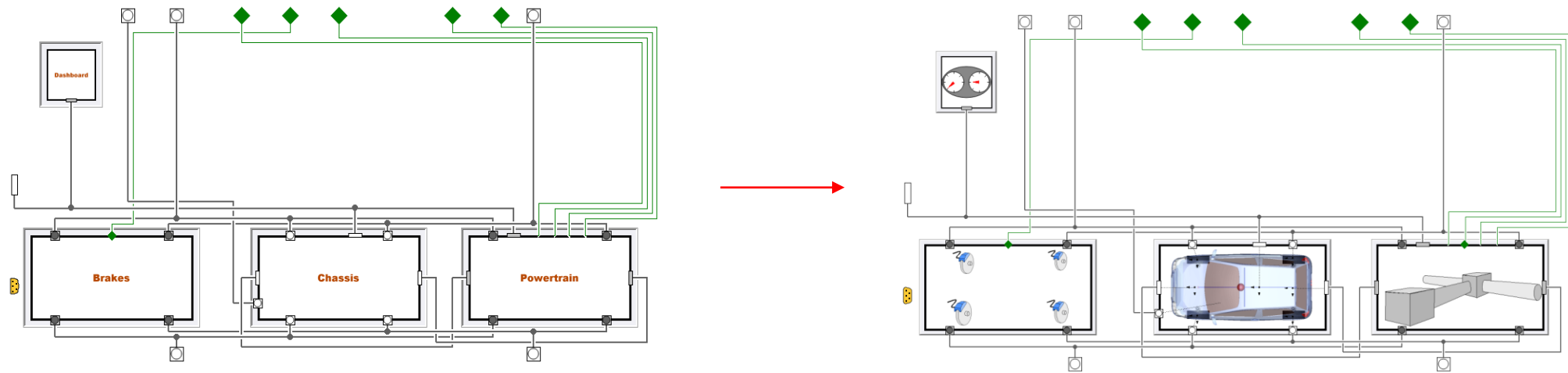
```
partial model EngineInterface
  Modelica.Mechanics.Rotational.Interfaces.Flange_a shaft
  annotation (...);
  Modelica.Blocks.Interfaces.RealInput throttle
  annotation (...);
end EngineInterface;
model Engine
  extends EngineInterface;
  ...
end Engine;
```

- **Engine** has all the properties of **EngineInterface**



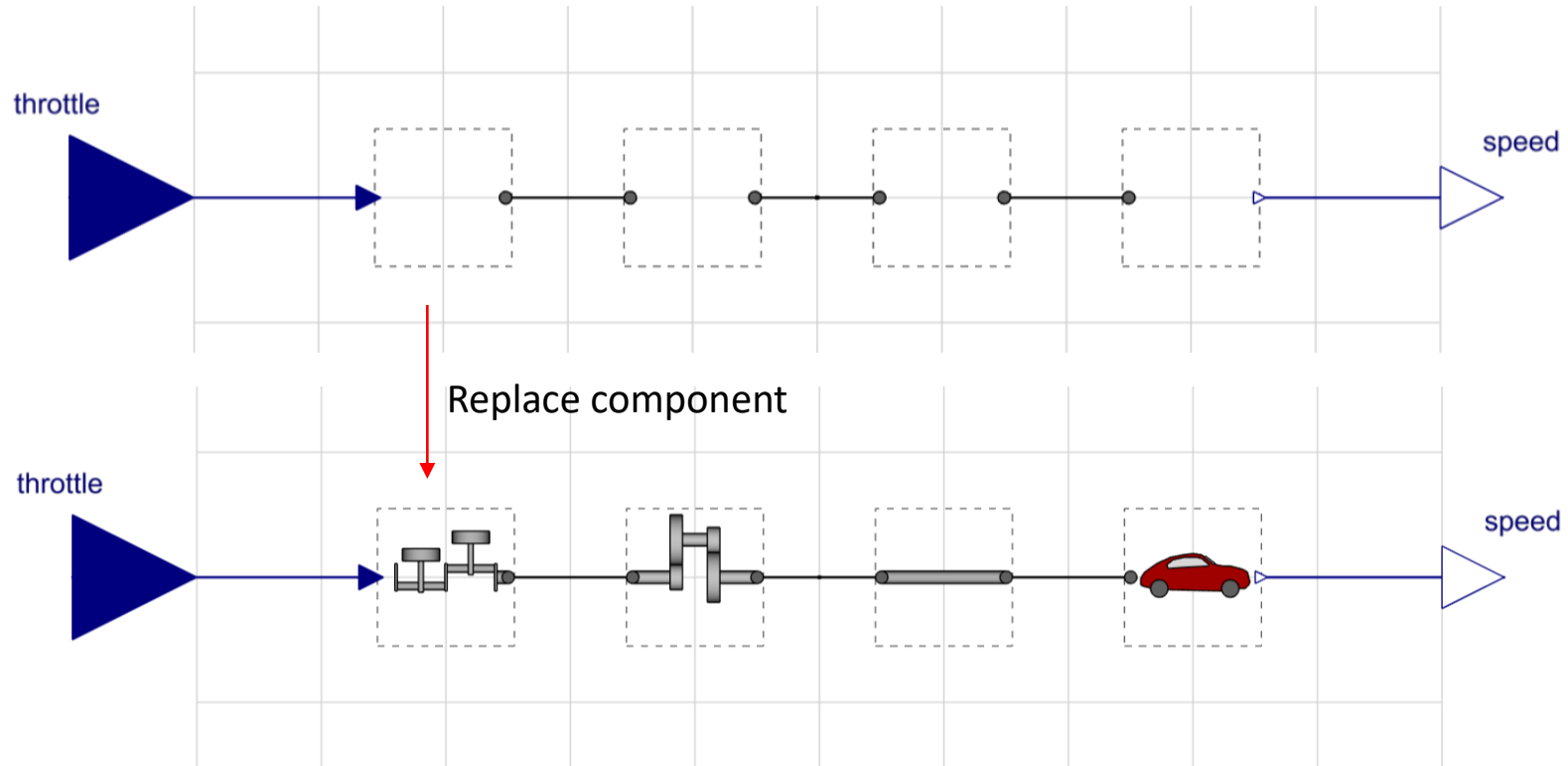
TEMPLATE CLASSES

- A template is a topology definition
- A template consist of
 - interfaces that act as placeholders
 - connections between the placeholders
- Using a template, configurations can be created by just specifying the components / subsystems



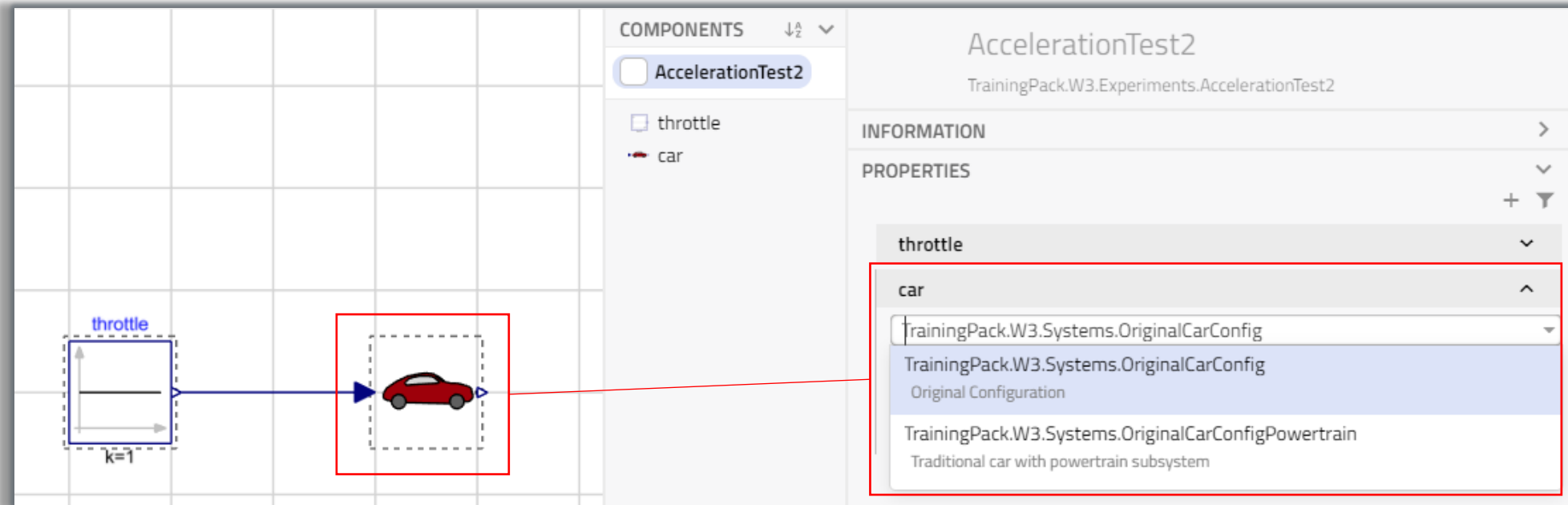
SYSTEM VARIANT

- If we have a template, with well defined interfaces, we can extend that and create a specific system variant:



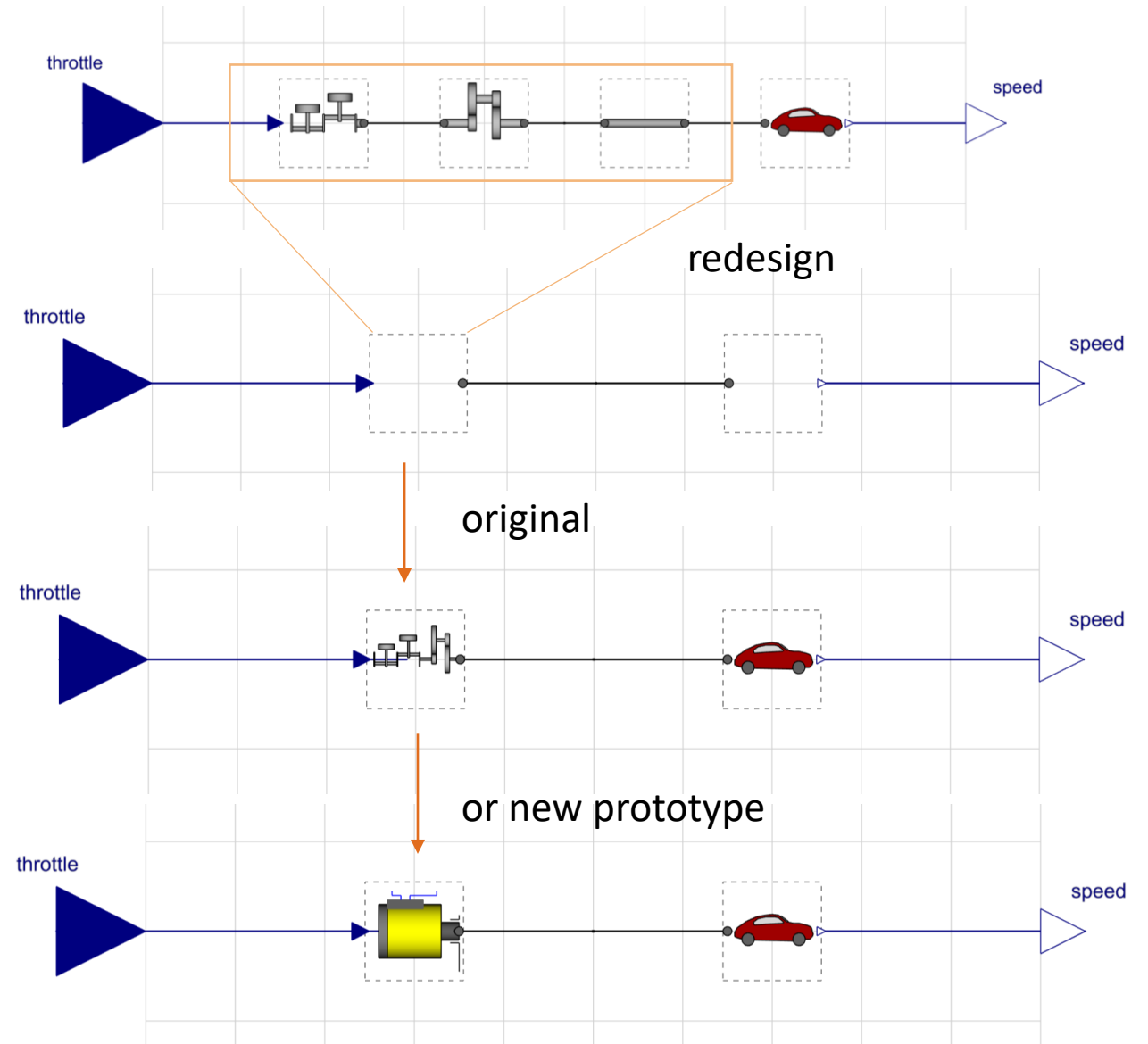
CHANGE CLASS THROUGH DROP-DOWN

- The parameter tab of the replaceable model will show a drop-down list
- The drop-down list will contain all matching choices
 - Matching choices here include any *car* model extending the *car* interface



TEMPLATE VARIATIONS

- Templates are easy to create
- Serve different architectures
- Reuses all subsystems





SYSTEM STICKIES AND VIEWS

STICKIES AND VIEWS

- Can be created for each subsystem

The screenshot displays the Modelon software interface for a subsystem named "IdealChassis". The main workspace shows a mechanical diagram with components: "driveLineFlange", "wheelInertia" (with $J=1$), "wheel" (with $\text{radius}=0.3$), "mass" (with $m=1400$), and "speedSensor". A parameter table is visible on the left:

J_wheel	1 kg·m ²
R_wheel	0.3 m
m_chassis	1400 kg

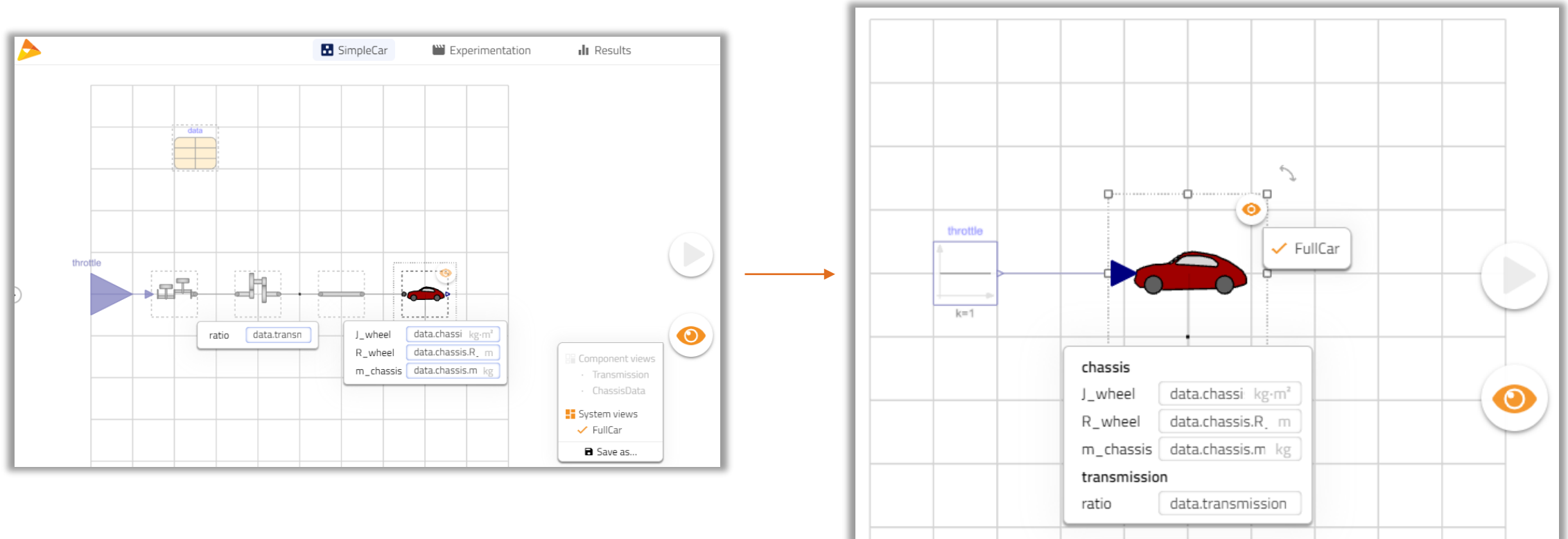
The right-hand panel shows the "IdealChassis" properties, including a "Variables" section with the following values:

J_wheel	1 kg·m ²
R_wheel	0.3 m
m_chassis	1400 kg
v_start	m/s

A context menu is open over the "mass" component, showing options: "System views", "ChassisData" (checked), and "Save as...".

STICKIES AND VIEWS AGGREGATION

- Multiple component views can be aggregated to a new system view



WORKSHOP 2.1

In this workshop you will:

- Browse a model library
- Inspect a hierarchical model
- Redesign an architecture
- Create new configurations